Description
The CBS-15 CAN instrumented servo provides a complete closed-loop actuator system for use in unmanned aerial vehicles. It features a high-frequency current-limiting feedback system, which is fully user configurable.

Servo control is provided over a high-speed CAN connection, fully compatible with the Piccolo series of autopilots and tightly integrated with the Currawong range of products. With a fully documented command set, it is ready to be integrated into other platforms with a simple protocol specification.

In addition to high speed CAN control of the servo position, real-time feedback of servo position, current, temperature and other data is available (at user-configurable rates) over CAN.

Each servo also features accelerometer-based vibration sensing, which provides a vibration analysis system distributed around the aircraft, with this data available via CAN. Accelerometer data can be sampled at up to 1 kHz for high-resolution vibration data.

In-built data logging is supported and can be controlled manually or driven by various internal trigger sources such as over-current or vibration events.

A variety of user-configurable warning thresholds (such as current, vibration and position error) provide vital real-time diagnostic information for configuring and monitoring the health of the aircraft.

Performance
- Voltage Range: 6 - 8.2 V
- Current Capability: 3 A per servo
- Torque: 15.8 kgcm (1.55 Nm) @ 8.2 V
- Speed: 0.11s @ 8.2 V
- Angular Range: ± 45°
- Control Frequency: Up to 333 Hz
- Temperature Range: -20°C to +60°C (-4°F to +140°F)
- Dimensions: 35 mm x 34 mm x 15 mm (excluding mount)
- Weight: 45 grams (1.6 oz)

Features
- High speed control over CAN
- Individually addressable servos with broadcast addressing supported
- Real-time feedback of multiple parameters
- Internal current measurement and limiting
- User-configurable input/output mapping for custom linearisation of control surfaces
- Accelerometer data with real-time vibration analysis
- High quality construction with all-metal body and gearing
- Seamless integration with Piccolo autopilot
- Compatible with Pixhawk/APM via UAVCAN
- Fully documented command set for integration with third party systems
- PC control software for servo control and configuration
- Full suite of graphing / logging / data analysis tools
- Fault monitoring and analysis
- Gear-wear diagnostics for servo health monitoring
- Servo keeps track of run-time information
- Internal high-speed data logging

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